

Dual axis fast steering mirror with position feedback MR-15-30



Optotune's dual axis fast steering mirror series MR-15-30 is the ideal choice for applications that require large deflections in a compact form factor. With a mirror size of 15 mm the MR-15-30 achieves up to $\pm 25^{\circ}$ mechanical tilt, which results in up to $\pm 50^{\circ}$ optical deflection. The mirror includes a position feedback system which allows it to be accurately controlled with a standard PID controller.

The actuator is based on proven technologies. In contrast to galvo mirror systems, the virtual rotation point is very close to the mirror surface. The mirror can be fabricated with various coatings such as protected gold or protected silver.

Advantages

- Large scan angle
- Compact
- Precise
- Reliable

Applications

- Automotive (LiDAR, dynamic headlights, ADAS)
- Vision (field of view (FOV) expansion, zoom)
- Biometric (eye-tracking) & diagnostic equipment
- 3D printing

The following table outlines the specifications of our standard MR-15-30. Custom mirror substrates and coatings are possible.

Mechanical specifications¹

| Calibration accuracy | 0.25 | 0 |
|--------------------------------------|---------------------------------------|---|
| | | ature) |
| Repeatability | 40 | μrad (RMS value over entire FOV, at room temper- |
| Sensor resolution (with 14bit ADC) | 22 | μrad |
| Zero drift (typical) | 100 | μrad /K RMS value over entire FOV |
| Magnetic shielding | yes | |
| Mechanical clamping | 4x M2 screws | |
| Weight | 29.3 | g |
| Height | 14.5 | mm |
| Housing diameter | 30.0 | mm |
| Center of rotation to mirror surface | 1.3 | mm |
| Mirror diameter | 15 | mm |
| Mechanical tilt angle dynamic | ±25 X axis; ±25 Y axis (circular FOV) | ۰ |
| Mechanical tilt angle DC | ±25 X axis; ±25 Y axis (circular FOV) | ٠ |
| Actuator Type | 4-Quadrant (2 axis, bi-directional) | |

¹ All angle values are with respect to mechanical angle.

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| | | 0.3°) long-term, MR-E-2 interpolates from 50 points | |
|---|---|--|--|
| Static displacement constant | 3 | rad/A Linearized full range | |
| Angular acceleration constant | 1.4 * 10^4 | rad/(A s²) Linearized full range | |
| Full scale bandwidth Sine wave (±25°) | 20 | Hz | |
| Small signal bandwidth (< ±0.1°) | 350 | Hz | |
| Large angle step settling time (20° step) | 13 | ms Measured with MR-E-2 driver board with 700mA peak current | |
| Small angle step settling time (0.1° step) | 3 | ms Measured with MR-E-2 driver board with 700mA peak current | |
| Optical specifications | | | |
| Surface finish | Protected gold, protected silver and dielectric (VIS), other custom coatings available | | |
| Reflectivity Protected Gold Protected Silver Dielectric VIS | Average >95% (800 nm < λ < 2 μm) >96% (450 nm < λ < 2 μm) >97% (450 nm < λ < 650 nm) | 45° AOI 45° AOI 45° ± 25° AOI | |
| Surface quality | 5/ 5x0.4; L1x0.06; C3x0.25; E 0.25 | ISO 10110 (60-40 Scratch-Dig) | |
| Mirror flatness | λ/2 | P-V @549nm (ISO Norm 10110) | |
| Electrical specifications | | | |
| Control interface | Analog interface for driver coils and for feedback readout | | |
| Max continuous current (RMS) | 0.3 | A Per coil. See thermal management. | |
| Peak current (10 ms duration) | 2 | Α | |
| Max mean actuation power | 1.5 | W both coils together | |
| Coil resistance (typical) | 11 | Ω | |
| Coil inductivity (typical) | 6 | mH | |
| Position sensor supply current (@1.5V) | 40 | mA | |
| Position sensor output current (typical) | 0.1 | mA 4 channels | |
| Temperature sensor | LM75B or equivalent | I2C-Address: 0x48 (+R/W bit) | |
| EEPROM ² | M24C08 or equivalent | I2C-Addresses: 0x50 to 0x53 (+R/W bit) | |
| Environmental specifications | | | |
| Operating temperature ³ | -20 to +85 | °C | |
| Storage temperature ³ | -40 to +85 | °C | |
| Shock | 105 g, 15 ms | DIN EN 60068-2-27 | |
| Vibration | 2 g, 10-150 Hz | ISO 9022-3-36 | |
| Cycle life | >10^9 | cycles | |
| | | | |

² EEPROM content definition is available upon request.

³ For larger temperature ranges contact Optotune.

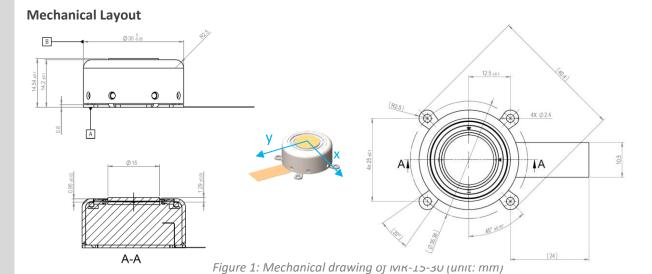
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Overview of available standard products

| Standard Product | Coating | Typical wavelength range |
|----------------------|-------------------------------|------------------------------|
| MR-15-30-G-25x25D | Protected gold | 800 nm - 2 μm |
| MR-15-30-PS-25x25D | Protected silver ⁴ | 400 nm - 2 μm (low humidity) |
| MR-15-30-DVIS-25x25D | Dielectric VIS | 450 nm - 650 nm |

⁴ DISCLAIMER: Despite the protective coating layer, it is best to avoid exposing silver mirrors to high humidity environments due to the associated tarnishing risk. For applications in the visible spectrum we strongly recommend the dielectric coating. Optotune declines the warranty due to humidity induced corrosion of the mirror coating.



When screwed in place, make sure the mirror is in firm contact with the heat sink. It is recommended that the heatsink dissipates about 2-5 W.

In terms of lateral alignment, it is recommended to use the outer diameter of the housing as an alignment feature.

Thermal Management

- Heat is generated as a function of actuation current and conducted away through the backside.
- Mount mirror firmly on a heat-conductive plate (copper or aluminum)
- Maximum dissipated power at max. static deflection is 0.25 W/channel (0.5 W total)
- For fast oscillations with high duty cycle the dissipated power is 4-5 W for the two axes combined.
- Max. operating temperature is 85°C

Packaging



Figure 2: MR-15-30 tray design

Single units ship in cardboard boxes. Larger volumes ship in ESD-safe and stackable PET trays of 25 MR-15-30 units each, sealed in a vacuum bag.



Static response

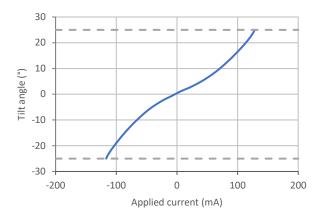


Figure 3: Mechanical tilt angle (limited to \pm 25°) versus applied current for single axis.

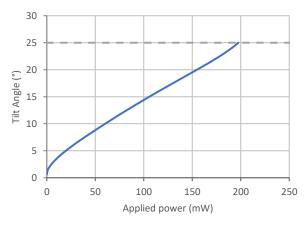


Figure 4: Tilt angle (mechanical) versus applied power (~8.6 mW/°)

Magnitude response

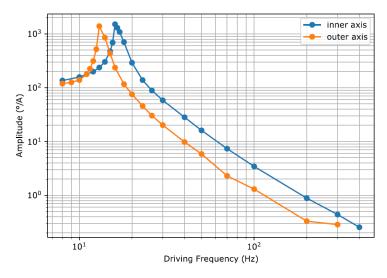


Figure 5: Magnitude response of outer axis (x) and inner axis (y) with sinusoidal excitation (15 mA amplitude).



Small step response

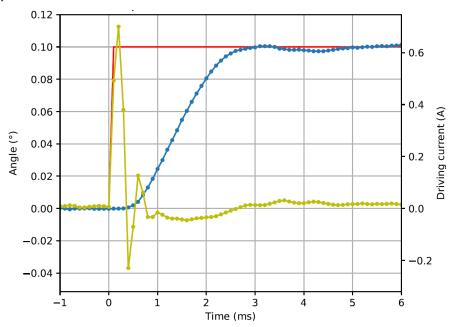


Figure 6: Small step settling time (blue curve) of outer axis for a 0.1° (mech.) step is 3 ms. Mirror operated with MR-E-2 PID controller. The yellow curve shows the corresponding driving current.

Large step response

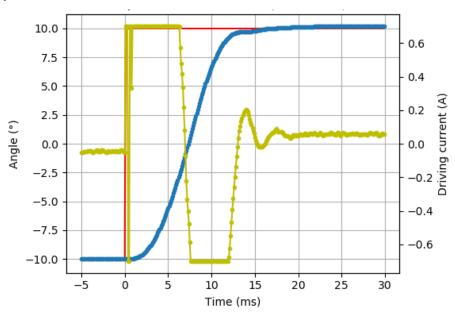


Figure 7: Large step settling time (blue curve) of outer axis for a 20° (mech.) step is 13 ms. Mirror operated with MR-E-2 PID controller. The yellow curve shows the corresponding driving current.



Maximum oscillation frequency

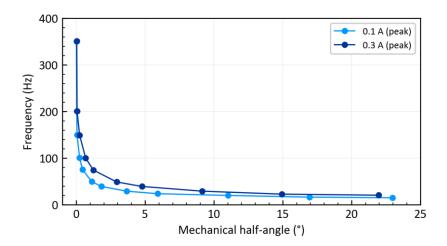


Figure 8: Max. oscillation speed (sinusoidal) of the outer axis as a function of the mechanical half-angle and driving current. The total optical FOV is 4 times the mechanical half-angle.

Reflectivity

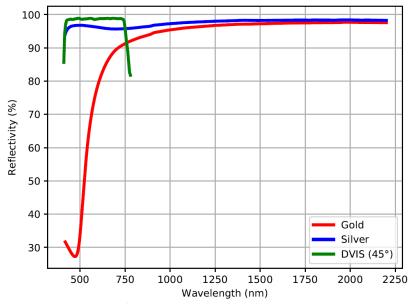


Figure 9: Reflectance spectra of our standard coatings.



Electrical connection and block diagram

| Pin | Function | Value | Pin | Function | Value |
|-----|-----------------|--------|-----|-------------------|---------------|
| | Position feed- | | | | |
| | back supply | | | | |
| 1 | Cathode | 40 mA | 11 | VDD | 3.3V |
| | Position feed- | 1.5 V | | | |
| _ | back supply An- | | | | |
| 2 | ode | | 12 | SCL | Digital 3.3 V |
| 3 | Y Coil + | | 13 | SDA | Digital 3.3 V |
| 4 | Y COII + | | 14 | GND | |
| | | | | Position feedback | |
| 5 | V Cail | | 15 | Anode | |
| | Y Coil - | | | Position feedback | |
| 6 | | ± 1 A | 16 | Y2 Cathode | |
| | | ± 15 V | | Position feedback | |
| 7 | X Coil + | ± 15 V | 17 | Y1 Cathode | currents |
| | X COII + | | | Position feedback | (μA range) |
| 8 | | | 18 | X2 Cathode | |
| | | | | Position feedback | |
| 9 | X Coil - | | 19 | X1 Cathode | |
| | A COII - | | | Position feedback | |
| 10 | | | 20 | Anode | |

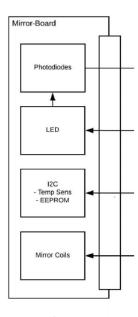


Table 1: Electrical pinout of the FPC cable (20 pins, 0.5 mm pitch) and block diagram of the MR-15-30

Beam clipping

Clipping of beam depends on beam diameter and tilt angle. For a beam incident at 0° beam sizes up to 10 mm can be used without clipping.

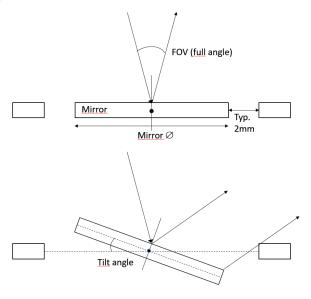


Figure 10: The maximum allowed beam diameter depends on input angle and mirror tilt angle.

Optotune can supply by request an EXCEL based calculation tool to evaluate beam clipping.



Environmental testing

The MR-15-30 is going through environmental and accelerated aging tests as outline in the table below.

| Test | Norm | Status |
|---|---------------------|---------|
| Mechanical cycling | - | Ongoing |
| 5-point star pattern running at 5 Hz, 2 billion cycles reached with no signs of fatigue, tested with MR-E-2 at room temperature | | |
| Accelerated gimbal test: | - | Pass |
| Gimbal subassembly tested at 8000 rpm for 800 million full rotations without significant degradation. | | |
| Temperature & Humidity | - | Pass |
| 85±2 °C, rel. hum. 45%, 1 week | | |
| Shock test 15 ms deceleration, three drops per axis. Mirror is not affected by shocks up to 105 g . | DIN EN 60068-2-27 | Pass |
| Vibration test | ISO 9022-3-36-03-01 | Pass |
| According to ISO 9022-3-36-03-01, 2 g, 10-150 Hz | | |
| Temperature Shock | 9022-15-03-1 | Pass |
| -40 to 55 °C, 2.5h/cycle, <20s transition time, 5 cycles | | |

Table 2: Environmental tests performed on the MR-15-30

Custom Products

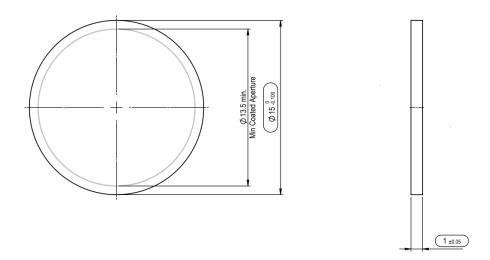


Figure 11: Dimensions of standard mirror substrate

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Optotune offers customizations of mirror substrates and coatings upon request. Substrates with a thickness of more than the standard 1 mm need to have a smaller diameter to maintain the full FOV. For a diameter of 12.7 mm the thickness can be as large as 3.5 mm. A change in inertia will influence mirror dynamics.

Safety and compliance

The product fulfills the RoHS, REACH, CE and flammability UV94 V-0 compliance standards. The customer is solely responsible to comply with all relevant safety regulations for integration and operation, including EMC compliance.

For more information on optical, mechanical and electrical parameters, please contact sales@optotune.com.